

IMACS PDE7 — SECOND TALK

**REVIEW OF SYMBOLIC SOFTWARE FOR
CALCULATING LIE SYMMETRIES OF
PARTIAL DIFFERENTIAL EQUATIONS**

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Calculation of Lie-point and Generalized Symmetries

- SPDE by Schwarz (Reduce, Scratchpad, 1986)
- Symmetries via exterior differential forms
by Kersten and Gragert (Reduce, 1987)
- Lie-Bäcklund symmetries by Fedorova, Korniyak and Fushchich
(Reduce, 1987)
- Crackstar by Wolf (Formac, 1987)
- Lie-point symmetries by Schwarzmeier
and Rosenau (Macysma, 1988)
- Special symmetries by Mikhailov (Pascal, 1988)

- LIE by Head (muMath, 1990)
- Lie program by Nucci (Reduce, 1990)
- PDELIE by Vafeades (Macsyma, 1990)
- DEliA by Bocharov (Pascal, 1990)
- SYM_DE by Steinberg (Macsyma, 1990)
- SYMCAL by Reid (Macsyma, 1990)
- SYMMGRP.MAX by Champagne, Hereman and Winter-
nitz (Macsyma, 1990)
- Lie symmetries by Herod, Berube, Wilcox
(Mathematica, in development 1992)

Example 1: The Korteweg-de Vries Equation

$$u_t + auu_x + u_{xxx} = 0$$

- one equation (parameter a)
- two independent variables t and x
- one dependent variable u
- vector field $\alpha = \eta^x \frac{\partial}{\partial x} + \eta^t \frac{\partial}{\partial t} + \varphi^u \frac{\partial}{\partial u}$

Format for SYMMGRP.MAX

- variables $x[1] = x$, $x[2] = t$, $u[1] = u$
- equation $e1 : u[1, [0, 1]] + a * u[1] * u[1, [1, 0]] + u[1, [3, 0]]$
- variable to be eliminated $v1 : u[1, [0, 1]]$
- coefficients of vectorfield in SYMMGRP.MAX:
eta[1] = η^x , eta[2] = η^t and phi[1] = φ^u

Format for PDELIE and SYM_DE

- variables: $[x, t]$ and $[u]$
- equation: $'\text{diff}(u, t) + a * u * '\text{diff}(u, x) + '\text{diff}(u, x, 3) = 0$
- variable to be eliminated: $'\text{diff}(u, t)$
- coefficients of vectorfield in PDELIE:
 $GX = \eta^x$, $GT = \eta^t$ and $FU = \varphi^u$
- coefficients of vectorfield in SYM_DE:
 $X_1 = \eta^x$, $X_2 = \eta^t$ and $Y_1 = \varphi^u$

Format for SPDE and LIE

- variables $X1 = x$, $X2 = t$, $U(1) = u$
- equation $e1 : U(1, 2) + A * U(1) * U(1, 1) + U(1, 1, 1, 1)$
- variable to be eliminated $U(1, 2)$
- coefficients of vectorfield in SPDE:
 $XI(1) = \eta^x$, $XI(2) = \eta^t$ and $ETA(1) = \varphi^u$
- coefficients of vectorfield in LIE:
 $XXX\#1 = \eta^x$, $XXX\#2 = \eta^t$ and $UUU\#1 = \varphi^u$

There are only eight determining equations

$$\frac{\partial \text{eta}[2]}{\partial u[1]} = 0$$

$$\frac{\partial \text{eta}[2]}{\partial x[1]} = 0$$

$$\frac{\partial \text{eta}[1]}{\partial u[1]} = 0$$

$$\frac{\partial^2 \text{phi}[1]}{\partial u[1]^2} = 0$$

$$\frac{\partial^2 \text{phi}[1]}{\partial u[1] \partial x[1]} - \frac{\partial^2 \text{eta}[1]}{\partial x[1]^2} = 0$$

$$\frac{\partial \text{phi}[1]}{\partial x[2]} + \frac{\partial^3 \text{phi}[1]}{\partial x[1]^3} + u[1] \frac{\partial \text{phi}[1]}{\partial x[1]} = 0$$

$$3 \frac{\partial^3 \text{phi}[1]}{\partial u[1] \partial x[1]^2} - \frac{\partial \text{eta}[1]}{\partial x[2]} - \frac{\partial^3 \text{eta}[1]}{\partial x[1]^3} + 2 u[1] \frac{\text{eta}[1]}{\partial x[1]} + \text{phi}[1] = 0$$

$$u[1] \frac{\partial \text{eta}[2]}{\partial x[2]} + 3 \frac{\partial^3 \text{phi}[1]}{\partial u[1] \partial x[1]^2} - \frac{\partial \text{eta}[1]}{\partial x[2]} - \frac{\partial^3 \text{eta}[1]}{\partial x[1]^3} - u[1] \frac{\text{eta}[1]}{\partial x[1]} + \text{phi}[1] = 0$$

The solution in the original variables

$$\begin{aligned} \eta^x &= k_1 + k_3 t - k_4 x \\ \eta^t &= k_2 - 3k_4 t \\ \varphi^u &= k_3 + 2 k_4 u \end{aligned}$$

The four infinitesimal generators are

$$\begin{aligned} G_1 &= \partial_x \\ G_2 &= \partial_t \\ G_3 &= t \partial_x + \partial_u \\ G_4 &= x \partial_x + 3 t \partial_t - 2 u \partial_u \end{aligned}$$

Equation is invariant under:

- translations G_1 and G_2
- Galilean boost G_3
- scaling G_4

Computation of the flows corresponding to G_1 thru G_4 shows that for any solution $u = f(x, t)$ of the KdV equation the transformed solutions

$$\tilde{u} = f(x - \epsilon, t)$$

$$\tilde{u} = f(x, t - \epsilon)$$

$$\tilde{u} = f(x - \epsilon, t) + \epsilon$$

$$\tilde{u} = e^{-2\epsilon} f(e^{-\epsilon}x, e^{-3\epsilon}t)$$

will solve the KdV equation

Note that ϵ is the parameter of the transformation group

Example 2: The Harry Dym Equation

$$u_t - u^3 u_{xxx} = 0$$

- one equation
- two independent variables t and x
- one dependent variable u
- vector field $\alpha = \eta^x \frac{\partial}{\partial x} + \eta^t \frac{\partial}{\partial t} + \varphi^u \frac{\partial}{\partial u}$

Format for SYMMGRP.MAX

- variables $x[1] = x$, $x[2] = t$, $u[1] = u$
- equation $e1 : u[1, [0, 1]] - u[1]^3 * u[1, [3, 0]]$
- variable to be eliminated $v1 : u[1, [0, 1]]$
- coefficients of vectorfield in SYMMGRP.MAX:
 $\text{eta}[1] = \eta^x$, $\text{eta}[2] = \eta^t$ and $\text{phi}[1] = \varphi^u$

Format for PDELIE and SYM_DE

- variables: $[x, t]$ and $[u]$
- equation: $'\text{diff}(u, t) - u^3 * '\text{diff}(u, x, 3) = 0$
- variable to be eliminated: $'\text{diff}(u, t)$
- coefficients of vectorfield in PDELIE:
 $GX = \eta^x$, $GT = \eta^t$ and $FU = \varphi^u$
- coefficients of vectorfield in SYM_DE:
 $X_1 = \eta^x$, $X_2 = \eta^t$ and $Y_1 = \varphi^u$

Format for SPDE and LIE

- variables $X1 = x$, $X2 = t$, $U(1) = u$
- equation $e1 : U(1, 2) - U(1)^3 * U(1, 1, 1, 1)$
- variable to be eliminated $U(1, 2)$
- coefficients of vectorfield in SPDE:
 $XI(1) = \eta^x$, $XI(2) = \eta^t$ and $ETA(1) = \varphi^u$
- coefficients of vectorfield in LIE:
 $XXX\#1 = \eta^x$, $XXX\#2 = \eta^t$ and $UUU\#1 = \varphi^u$

There are only eight determining equations,
in SYMMGRP.MAX notation

$$\frac{\partial \text{eta}[2]}{\partial u[1]} = 0$$

$$\frac{\partial \text{eta}[2]}{\partial x[1]} = 0$$

$$\frac{\partial \text{eta}[1]}{\partial u[1]} = 0$$

$$\frac{\partial^2 \text{phi}[1]}{\partial u[1]^2} = 0$$

$$\frac{\partial^2 \text{phi}[1]}{\partial u[1] \partial x[1]} - \frac{\partial^2 \text{eta}[1]}{\partial x[1]^2} = 0$$

$$\frac{\partial \text{phi}[1]}{\partial x[2]} - u[1]^3 \frac{\partial^3 \text{phi}[1]}{\partial x[1]^3} = 0$$

$$3u[1]^3 \frac{\partial^3 \text{phi}[1]}{\partial u[1] \partial x[1]^2} + \frac{\partial \text{eta}[1]}{\partial x[2]} - u[1]^3 \frac{\partial^3 \text{eta}[1]}{\partial x[1]^3} = 0$$

$$u[1] \frac{\partial \text{eta}[2]}{\partial x[2]} - 3u[1] \frac{\partial \text{eta}[1]}{\partial x[1]} + 3 \text{phi}[1] = 0$$

The solution in the original variables

$$\begin{aligned}\eta^x &= k_1 + k_3 x + k_5 x^2 \\ \eta^t &= k_2 - 3k_4 t \\ \varphi^u &= (k_3 + k_4 + 2k_5 x) u\end{aligned}$$

The five infinitesimal generators are

$$\begin{aligned}G_1 &= \partial_x \\ G_2 &= \partial_t \\ G_3 &= x\partial_x + u\partial_u \\ G_4 &= -3t\partial_t + u\partial_u \\ G_5 &= x^2\partial_x + 2xu\partial_u\end{aligned}$$

Equation is invariant under:

- translations G_1 and G_2
- scaling G_3 and G_4
- what else ?

Computation of the flow corresponding to G_5

$$\begin{aligned}\frac{d\tilde{x}}{d\epsilon} &= \tilde{x}^2 & \tilde{x}(0) &= x \\ \frac{d\tilde{t}}{d\epsilon} &= 0 & \tilde{t}(0) &= t \\ \frac{d\tilde{u}}{d\epsilon} &= 2\tilde{x}\tilde{u} & \tilde{u}(0) &= u\end{aligned}\tag{1}$$

ϵ is the parameter of the transformation group

One obtains

$$\begin{aligned}\tilde{x}(\epsilon) &= \frac{x}{1 - \epsilon x} \\ \tilde{t}(\epsilon) &= t \\ \tilde{u}(\epsilon) &= \frac{u}{(1 - \epsilon x)^2}\end{aligned}$$

Conclusion: for any solution $u = f(x, t)$ of the Harry Dym equation the transformed solution

$$\tilde{u}(\tilde{x}, \tilde{t}) = (1 + \epsilon\tilde{x})^2 f\left(\frac{\tilde{x}}{1 + \epsilon\tilde{x}}, \tilde{t}\right)$$

will solve

$$\tilde{u}_{\tilde{t}} - \tilde{u}^3 \tilde{u}_{\tilde{x}\tilde{x}\tilde{x}} = 0$$

Example 3: The cylindrical KdV Equation

$$u_t + 6uu_x + u_{xxx} + \frac{1}{2t}u = 0$$

- one equation with time-dependent coefficient
- two independent variables t and x
- one dependent variable u
- vector field $\alpha = \eta^x \frac{\partial}{\partial x} + \eta^t \frac{\partial}{\partial t} + \varphi^u \frac{\partial}{\partial u}$

Format for SYMMGRP.MAX

- variables $x[1] = x$, $x[2] = t$, $u[1] = u$
- equation $e1 : u[1, [0, 1]] + 6 * u[1] * u[1, [1, 0]] + u[1, [3, 0]] + u[1]/(2 * x[2])$
- variable to be eliminated $v1 : u[1, [0, 1]]$
- coefficients of vectorfield in SYMMGRP.MAX:
 $\text{eta}[1] = \eta^x$, $\text{eta}[2] = \eta^t$ and $\text{phi}[1] = \varphi^u$

There are only eight determining equations (not shown)

The solution in the original variables

$$\begin{aligned}\eta^x &= k_1 + k_2 x + 2 k_3 \sqrt{t} + 2 k_4 x \sqrt{t} \\ \eta^t &= 3 k_2 t + 4 k_4 t \sqrt{t} \\ \varphi^u &= -2 k_2 u - 4 k_4 u \sqrt{t} + \frac{1}{6\sqrt{t}} (k_4 x + k_3)\end{aligned}$$

The four infinitesimal generators are

$$G_1 = \partial_x$$

$$G_2 = x \partial_x + 3 t \partial_t - 2 u \partial_u$$

$$G_3 = 12 \sqrt{t} \partial_x + \frac{1}{\sqrt{t}} \partial_u$$

$$G_4 = 12 x \sqrt{t} \partial_x + 24 t \sqrt{t} \partial_t - 24\sqrt{t} u \partial_u + x \frac{1}{\sqrt{t}} \partial_u$$

Example 4: The Nonlinear Schrödinger Equation

$$iu_t + u_{xx} + 2|u|^2u = 0$$

Split in real and imaginary parts via $u = v + iw$

$$\begin{aligned}v_t + v_{xx} + 2(v^2 + w^2)w &= 0 \\w_t - w_{xx} - 2(v^2 + w^2)v &= 0\end{aligned}$$

- two coupled equations
- two independent variables t and x
- two dependent variable v and w
- vector field $\alpha = \eta^x \frac{\partial}{\partial x} + \eta^t \frac{\partial}{\partial t} + \varphi^v \frac{\partial}{\partial v} + \varphi^w \frac{\partial}{\partial w}$

Format for SYMMGRP.MAX

- variables $x[1] = x$, $x[2] = t$, $u[1] = u$, $u[2] = w$
- equations
 $e1 : u[1, [0, 1]] + u[2, [2, 0]] + 2 * u[2] * (u[1]^2 + u[2]^2)$
 $e2 : u[2, [0, 1]] - u[1, [2, 0]] - 2 * u[1] * (u[1]^2 + u[2]^2)$
- variables to be eliminated $v1 : u[1, [0, 1]]$ and $v2 : u[2, [0, 1]]$
- coefficients of vectorfield in SYMMGRP.MAX:
 $\text{eta}[1] = \eta^x$, $\text{eta}[2] = \eta^t$, $\text{phi}[1] = \varphi^v$ and $\text{phi}[2] = \varphi^w$

There are 20 determining equations

The solution in the original variables

$$\begin{aligned}\eta^x &= k_1 + k_4 x + 2 k_5 t \\ \eta^t &= k_2 + 2k_4 t \\ \varphi^v &= -k_3 w - k_4 v - k_5 x w \\ \varphi^w &= k_3 v - k_4 w + k_5 x v\end{aligned}$$

The five infinitesimal generators are

$$\begin{aligned}G_1 &= \partial_x \\ G_2 &= \partial_t \\ G_3 &= v \partial_w - w \partial_v \\ G_4 &= 2 t \partial_t + x \partial_x - v \partial_v - w \partial_w \\ G_5 &= 2 t \partial_x - x w \partial_v + x v \partial_w\end{aligned}$$

Equation is invariant under:

- translations G_1 and G_2
- rotation G_3
- dilation or scaling G_4
- Galilean boost or inversion G_5

Example 5: The Ernst Equations

$$\begin{aligned}F\nabla^2 F &= (\nabla F)^2 - (\nabla G)^2 \\F\nabla^2 G &= 2(\nabla F) \cdot (\nabla G)\end{aligned}$$

With $F(\rho, z)$, $G(\rho, z)$ and $\rho = \sqrt{x^2 + y^2}$

$$\begin{aligned}\nabla^2 F &= F_{\rho\rho} + \rho^{-1} + F_{zz} \\|\nabla F|^2 &= F_\rho^2 + F_z^2\end{aligned}$$

$$\begin{aligned}F[\rho(F_{\rho\rho} + F_{zz}) + F_\rho] - \rho(F_\rho^2 + F_z^2 - G_\rho^2 - G_z^2) &= 0 \\F[\rho(G_{\rho\rho} + G_{zz}) + G_\rho] - 2\rho(F_\rho G_\rho + F_z G_z) &= 0\end{aligned}$$

- two coupled equations
- two independent variables ρ and z
- two dependent variable F and G
- vector field $\alpha = \eta^\rho \frac{\partial}{\partial \rho} + \eta^z \frac{\partial}{\partial z} + \varphi^F \frac{\partial}{\partial F} + \varphi^G \frac{\partial}{\partial G}$

Format for SYMMGRP.MAX

- variables $x[1] = \rho$, $x[2] = z$, $u[1] = F$, $u[2] = G$
- equations
$$e1 : u[1] * (x[1] * (u[1, [2, 0]] + u[1, [0, 2]]) + u[1, [1, 0]])$$
$$- x[1] * (u[1, [1, 0]]^2 + u[1, [0, 1]]^2 - u[2, [1, 0]]^2 - u[2, [0, 1]]^2)$$
$$e2 : u[1] * (x[1] * (u[2, [2, 0]] + u[2, [0, 2]]) + u[2, [1, 0]])$$
$$- 2 * x[1] * (u[1, [1, 0]] * u[2, [1, 0]] + u[1, [0, 1]] * u[2, [0, 1]])$$
- variables to be eliminated $v1 : u[1, [2, 0]]$ and $v2 : u[2, [2, 0]]$
- coefficients of vectorfield in SYMMGRP.MAX:
 $\text{eta}[1] = \eta^\rho$, $\text{eta}[2] = \eta^z$, $\text{phi}[1] = \varphi^F$ and $\text{phi}[2] = \varphi^G$

There are 25 determining equations (not shown)

The solution in the original variables

$$\begin{aligned}\eta^\rho &= k_3 \rho \\ \eta^z &= k_1 + k_3 z \\ \varphi^F &= k_4 F + 2 k_5 F G \\ \varphi^G &= k_2 + k_4 G - k_5 (F^2 - G^2)\end{aligned}$$

The five infinitesimal generators are

$$\begin{aligned}G_1 &= \partial_z \\ G_2 &= \partial_G \\ G_3 &= \rho \partial_\rho + z \partial_z \\ G_4 &= F \partial_F + G \partial_G \\ G_5 &= 2 F G \partial_F - (F^2 - G^2) \partial_G\end{aligned}$$

Example 6: The Karpman Equations

The Karpman equations describe the effect of modulation instability of a high frequency (whistler) wave due to its resonant parametric interaction with a low frequency wave in a plasma

$$i(\psi_t + w_1 \psi_z) + \frac{1}{2}[s_1 (\psi_{xx} + \psi_{yy}) + s_2 \psi_{zz}] - a_1 \nu \psi = 0$$

$$\nu_{tt} - (w_2)^2 (\nu_{xx} + \nu_{yy} + \nu_{zz}) - a_2 (|\psi|_{xx}^2 + |\psi|_{yy}^2 + |\psi|_{zz}^2) = 0$$

ψ is the complex amplitude of the whistler wave

ν is the particle density of the plasma

a_1, a_2, s_1, s_2, w_1 and w_2 are real constants

Split ψ in real and imaginary parts

$$\psi = \rho(x, y, z, t) \exp[i\phi(x, y, z, t)]$$

$$\rho_t + w_1 \rho_z + \left[\frac{s_1}{2} (2\rho_x \phi_x + 2\rho_y \phi_y + \rho \phi_{xx} + \rho \phi_{yy}) + \frac{s_2}{2} (2\rho_z \phi_z + \rho \phi_{zz}) \right] = 0$$

$$\phi_t + w_1 \phi_z - \left[\frac{s_1}{2} \left(\frac{\rho_{xx}}{\rho} + \frac{\rho_{yy}}{\rho} - \phi_x^2 - \phi_y^2 \right) + \frac{s_2}{2} \left(\frac{\rho_{zz}}{\rho} - \phi_z^2 \right) \right] + a_1 \nu = 0$$

$$\nu_{tt} - (w_2)^2 (\nu_{xx} + \nu_{yy} + \nu_{zz}) - 2a_2 \rho (\rho_{xx} + \rho_{yy} + \rho_{zz}) - 2a_2 (\rho_x^2 + \rho_y^2 + \rho_z^2) = 0$$

- three coupled equations
- four independent variables x, y, z and t
- three dependent variables ρ, ϕ and ν
- vector field

$$\alpha = \eta^x \frac{\partial}{\partial x} + \eta^y \frac{\partial}{\partial y} + \eta^z \frac{\partial}{\partial z} + \eta^t \frac{\partial}{\partial t} + \varphi^\rho \frac{\partial}{\partial \rho} + \varphi^\phi \frac{\partial}{\partial \phi} + \varphi^\nu \frac{\partial}{\partial \nu}$$

Format for SYMMGRP.MAX

- variables

$$\begin{array}{ll} x \longmapsto x[1] & \rho \longmapsto u[1] \\ y \longmapsto x[2] & \phi \longmapsto u[2] \\ z \longmapsto x[3] & \nu \longmapsto u[3] \\ t \longmapsto x[4] & \end{array} \quad (2)$$

- typical datafile (next page)
- variables to be eliminated
 - v1 : u[1,[0,0,0,1]]
 - v2 : u[2,[0,0,0,1]]
 - v3 : u[3,[0,0,0,2]]

There are 69 determining equations (not shown)

The solution in the original variables

$$\begin{aligned}\eta^x &= k_1 y + k_2 & \varphi^\rho &= 0 \\ \eta^y &= -k_1 x + k_3 & \varphi^\phi &= k_7 a_1 t^2 + k_8 a_1 t + k_9 \\ \eta^z &= k_4 & \varphi^\nu &= -2 k_7 t - k_8 \\ \eta^t &= k_5\end{aligned}\quad (3)$$

The eight infinitesimal generators are

$$\begin{aligned}G_1 &= \partial_x & G_5 &= y\partial_x - x\partial_y \\ G_2 &= \partial_y & G_6 &= \partial_\phi \\ G_3 &= \partial_z & G_7 &= a_1 t \partial_\phi - \partial_\nu \\ G_4 &= \partial_t & G_8 &= a_1 t^2 \partial_\phi - 2t \partial_\nu\end{aligned}\quad (4)$$

Typical Datafile

p : 4 \$

q : 3 \$

m : 3 \$

parameters : [a1,a2,s1,s2,w1,w2] \$

warnings : true \$

sublisteqs : [all] \$

info_given : false \$

highest_derivatives : all \$

subst_deriv_of_vi : false \$

e1 : $u[1,[0,0,0,1]]+w1*u[1,[0,0,1,0]]+(1/2)*(s1*(2*u[1,[1,0,0,0]]*u[2,[1,0,0,0]]+2*u[1,[0,1,0,0]]*u[2,[0,1,0,0]]+u[1]*u[2,[2,0,0,0]]+u[1]*u[2,[0,2,0,0]])+s2*(2*u[1,[0,0,1,0]]*u[2,[0,0,1,0]]+u[1]*u[2,[0,0,2,0]]))$;

e2 : $u[2,[0,0,0,1]]+w1*u[2,[0,0,1,0]]-(1/2)*(s1*(u[1,[2,0,0,0]]/u[1]+u[1,[0,2,0,0]]/u[1]-u[2,[1,0,0,0]]^2-u[2,[0,1,0,0]]^2)+s2*(u[1,[0,0,2,0]]/u[1]-u[2,[0,0,1,0]]^2))+a1*u[3]$;

e3 : $u[3,[0,0,0,2]]-v2^2*(u[3,[2,0,0,0]]+u[3,[0,2,0,0]]+u[3,[0,0,2,0]])-2*a2*u[1]*(u[1,[2,0,0,0]]+u[1,[0,2,0,0]]+u[1,[0,0,2,0]])-2*a2*(u[1,[1,0,0,0]]^2+u[1,[0,1,0,0]]^2+u[1,[0,0,1,0]]^2)$;

v1 : $u[1,[0,0,0,1]]$;

v2 : $u[2,[0,0,0,1]]$;

v3 : $u[3,[0,0,0,2]]$;

Example 8: The Magneto-Hydro-Dynamics Eqs.

$$\begin{aligned}\frac{\partial \rho}{\partial t} + (\vec{v} \cdot \nabla) \rho + \rho \nabla \cdot \vec{v} &= 0 \\ \rho \left(\frac{\partial \vec{v}}{\partial t} + (\vec{v} \cdot \nabla) \vec{v} \right) + \nabla \left(p + \frac{1}{2} \vec{H}^2 \right) - (\vec{H} \cdot \nabla) \vec{H} &= \vec{0} \\ \frac{\partial \vec{H}}{\partial t} + (\vec{v} \cdot \nabla) \vec{H} + \vec{H} \nabla \cdot \vec{v} - (\vec{H} \cdot \nabla) \vec{v} &= \vec{0} \\ \nabla \cdot \vec{H} &= 0 \\ \frac{\partial}{\partial t} \left(\frac{p}{\rho^\kappa} \right) + (\vec{v} \cdot \nabla) \left(\frac{p}{\rho^\kappa} \right) &= 0\end{aligned}$$

p pressure

ρ mass density

κ coefficient of viscosity

\vec{v} fluid velocity

\vec{H} magnetic field

- nine coupled scalar equations
- four independent variables x, y, z and t
- eight dependent variables $\rho, p, v_x, v_y, v_z, H_x, H_y$ and H_z
- vector field

$$\alpha = \eta^x \frac{\partial}{\partial x} + \eta^y \frac{\partial}{\partial y} + \eta^z \frac{\partial}{\partial z} + \eta^t \frac{\partial}{\partial t}$$

$$\begin{aligned}
& + \varphi^\rho \frac{\partial}{\partial \rho} + \varphi^p \frac{\partial}{\partial p} \\
& + \varphi^{v_x} \frac{\partial}{\partial v_x} + \varphi^{v_y} \frac{\partial}{\partial v_y} + \varphi^{v_z} \frac{\partial}{\partial v_z} \\
& + \varphi^{H_x} \frac{\partial}{\partial H_x} + \varphi^{H_y} \frac{\partial}{\partial H_y} + \varphi^{H_z} \frac{\partial}{\partial H_z}
\end{aligned}$$

Format for SYMMGRP.MAX

- variables

$$\begin{array}{ll}
x \longmapsto x[1] & v_x \longmapsto u[3] \\
y \longmapsto x[2] & v_y \longmapsto u[4] \\
z \longmapsto x[3] & v_z \longmapsto u[5] \\
t \longmapsto x[4] & H_x \longmapsto u[6] \\
\rho \longmapsto u[1] & H_y \longmapsto u[7] \\
p \longmapsto u[2] & H_z \longmapsto u[8]
\end{array} \tag{5}$$

- typical datafile (next page)
- variables to be eliminated vi ($i : 1...9$)

There are 222 determining equations (not shown)

The solution in the original variables is

$$\eta^x = k_2 + k_5 t - k_8 y - k_9 z + k_{11} x$$

$$\eta^y = k_3 + k_6 t + k_8 x - k_{10} z + k_{11} y$$

$$\eta^z = k_4 + k_7 t + k_9 x + k_{10} y + k_{11} z$$

$$\eta^t = k_1 + k_{12} t$$

$$\varphi^\rho = -2 (k_{11} - k_{12} - k_{13}) \rho$$

$$\varphi^p = 2 k_{13} p$$

$$\varphi^{v_x} = k_5 - k_8 v_y - k_9 v_z + (k_{11} - k_{12})v_x$$

$$\varphi^{v_y} = k_6 + k_8 v_x - k_{10} v_z + (k_{11} - k_{12})v_y$$

$$\varphi^{v_z} = k_7 + k_9 v_x + k_{10} v_y + (k_{11} - k_{12})v_z$$

$$\varphi^{H_x} = k_{13} H_x - k_8 H_y - k_9 H_z$$

$$\varphi^{H_y} = k_{13} H_y + k_8 H_x - k_{10} H_z$$

$$\varphi^{H_z} = k_{13} H_z + k_9 H_x + k_{10} H_y$$

The thirteen infinitesimal generators are

$$G_1 = \partial_t$$

$$G_2 = \partial_x$$

$$G_3 = \partial_y$$

$$G_4 = \partial_z$$

$$G_5 = t\partial_x + \partial_{v_x}$$

$$G_6 = t\partial_y + \partial_{v_y}$$

$$G_7 = t\partial_z + \partial_{v_z}$$

$$G_8 = x\partial_y - y\partial_x + v_x\partial_{v_y} - v_y\partial_{v_x} + H_x\partial_{H_y} - H_y\partial_{H_x}$$

$$G_9 = y\partial_z - z\partial_y + v_y\partial_{v_z} - v_z\partial_{v_y} + H_y\partial_{H_z} - H_z\partial_{H_y}$$

$$G_{10} = z\partial_x - x\partial_z + v_z\partial_{v_x} - v_x\partial_{v_z} + H_z\partial_{H_x} - H_x\partial_{H_z}$$

$$G_{11} = x\partial_x + y\partial_y + z\partial_z - 2\rho\partial_\rho + v_x\partial_{v_x} + v_y\partial_{v_y} + v_z\partial_{v_z}$$

$$G_{12} = t\partial_t + 2\rho\partial_\rho - (v_x\partial_{v_x} + v_y\partial_{v_y} + v_z\partial_{v_z})$$

$$G_{13} = 2\rho\partial_\rho + 2p\partial_p + H_x\partial_{H_x} + H_y\partial_{H_y} + H_z\partial_{H_z}$$

Equations are invariant under:

- translations G_2 through G_4
- Galilean boosts G_5 through G_7
- rotations G_8 through G_{10}
- dilations G_{11} through G_{13}

Software Performance for $u_t + auu_x + u_{xxx} = 0$

Korteweg-de Vries	PC LIE Head	PDELIE Vafeades	SYM_DE Steinberg	SPDE Schwarz	SYMMGRP Hereman
Determining Equations	7	?	4 ‡	?	8
Solved Automatically	Y	Y	N	Y	N
Correct Solution	Y	Y †	Y	Y	Y
Errors	N	N	N	N	N
Trouble		parameter	parameter		
Notes		† $a = 1$	‡ 2 if $a = 1$		

Software Performance for $u_t - u^3 u_{xxx} = 0$

Harry Dym Eq	PC LIE Head	PDELIE Vafeades	SYM_DE Steinberg	SPDE Schwarz	SYMMGRP Hereman
Determining Equations	7	?	N	?	8
Solved Automatically	Y	Y	N	?	N
Correct Solution	Y	Y	N	?	Y
Errors	N	N	Y	?	N
Trouble			sym_oneterm cannot solve $\frac{DA2}{DU}U^6 = 0$		
Notes					

Software Performance for $u_t + 6uu_x + u_{xxx} + \frac{1}{2t}u = 0$

cylindrical KdV	PC LIE Head	PDELIE Vafeades	SYM.DE Steinberg	SPDE Schwarz	SYMMGRP Hereman
Determining Equations	7	?	3	?	8
Solved Automatically	Y	Y	N	?	N
Correct Solution	Y	N	Y	?	Y
Errors	N	N	N	?	N
Trouble					
Notes		incomplete			

Software Performance for $iu_t + u_{xx} + 2|u|^2u = 0$

NL Schrödinger	PC LIE Head	PDELIE Vafeades	SYM.DE Steinberg	SPDE Schwarz	SYMMGRP Hereman
Determining Equations	15	?	10	40	20
Solved Automatically	Y	N	N	Y	N
Correct Solution	Y	N	Y	Y	Y
Errors	N	Y	N	N	N
Trouble		member atomic			
Notes					

Software Performance for

$$F[\rho(F_{\rho\rho} + F_{zz}) + F_\rho] - \rho(F_\rho^2 + F_z^2 - G_\rho^2 - G_z^2) = 0$$

$$F[\rho(G_{\rho\rho} + G_{zz}) + G_\rho] - 2\rho(F_\rho G_\rho + F_z G_z) = 0$$

Ernst Equations	PC LIE Head	PDELIE Vafeades	SYM_DE Steinberg	SPDE Schwarz	SYMMGRP Hereman
Determining Equations	15	?	23	21	25
Solved Automatically	Y	N	N	N ‡	N
Correct Solution	Y †	N	Y	N	Y
Errors	N	Y	N	Y	N
Trouble		member atomic		‡ info given	
Notes	† docheck twice			wrong in paper	

Software Performance for

$$i(\psi_t + w_1 \psi_z) + \frac{1}{2}[s_1 (\psi_{xx} + \psi_{yy}) + s_2 \psi_{zz}] - a_1 \nu \psi = 0$$

$$\nu_{tt} - (w_2)^2 (\nu_{xx} + \nu_{yy} + \nu_{zz}) - a_2 (|\psi|_{xx}^2 + |\psi|_{yy}^2 + |\psi|_{zz}^2) = 0$$

Karpman Eqs	PC LIE Head	PDELIE Vafeades	SYM_DE Steinberg	SPDE Schwarz	SYMMGRP Hereman
Determining Equations	74	?	? †	?	69
Solved Automatically	Y	?	?	?	N
Correct Solution	Y	?	?	?	Y
Errors	N	?	?	?	N
Trouble			† ran for hours on SUN station		
Notes					

Software Performance for

$$\begin{aligned} \frac{\partial \rho}{\partial t} + (\vec{v} \cdot \nabla) \rho + \rho \nabla \cdot \vec{v} &= 0 \\ \rho \left(\frac{\partial \vec{v}}{\partial t} + (\vec{v} \cdot \nabla) \vec{v} \right) + \nabla \left(p + \frac{1}{2} \vec{H}^2 \right) - (\vec{H} \cdot \nabla) \vec{H} &= \vec{0} \\ \frac{\partial \vec{H}}{\partial t} + (\vec{v} \cdot \nabla) \vec{H} + \vec{H} \nabla \cdot \vec{v} - (\vec{H} \cdot \nabla) \vec{v} &= \vec{0} \\ \nabla \cdot \vec{H} &= 0 \\ \frac{\partial}{\partial t} \left(\frac{p}{\rho^\kappa} \right) + (\vec{v} \cdot \nabla) \left(\frac{p}{\rho^\kappa} \right) &= 0 \end{aligned}$$

MHD Equations	PC LIE Head	PDELIE Vafeades	SYM_DE Steinberg	SPDE Schwarz	SYMMGRP Hereman
Determining Equations	N †	?	?	160	222
Solved Automatically	?	?	?	Y ‡	N
Correct Solution	?	?	?	?	Y
Errors	?	?	?	?	N
Notes	† Out of Memory			‡ Used CRAY XMP	

Documentation and Examples

	PC LIE Head	PDELIE Vafeades	SYM_DE Steinberg	SPDE Schwarz	SYMMGRP Hereman
Source	Y	N	N	Y	Y
Available	PC	Macsyma	Macsyma	Reduce	CPC Lib
Usage Readme	1	1	1	1	1
Demo files	10	0	5	1	1
Worked Cases	10	5	12	6	12
Test Cases	30	12	20	30	50
Papers	1 †	1	1	2	1
Notes	† planned				

Tasks of the Programs

	PC LIE Head	PDELIE Vafeades	SYM_DE Steinberg	SPDE Schwarz	SYMMGRP Hereman
Determining eqs	Y	Y	Y	Y	Y
Solve (auto)	Y	Y	Y	Y	N
Solve (inter)	Y	Y	Y	Y	Y
Check coeff	Y	Y	Y	Y	Y
Generators	Y	Y	Y	Y	N
Commutators	Y	N	N	Y	N
Invariants	N	Y	Y †	N	N
Similarity sol	N	Y	N	N	N
General symm	N	Y	N ?	N	N
Other		type of symmetry	pol sol † lin system		large systems